

S. 87, A 22

$$(1) \ddot{x} + \gamma = \sin 2t$$

$$x(0) = 1, \quad \gamma(0) = 0$$

$$(2) \dot{\gamma} - x = \cos 2t$$

$$(1) \Rightarrow (3) \gamma = -\dot{x} + \sin 2t \Rightarrow (4) \dot{\gamma} = -\ddot{x} + 2\cos 2t$$

$$(4) \text{ in } (2) \Rightarrow -\ddot{x} + 2\cos 2t - x = \cos 2t$$

$$\Rightarrow -\ddot{x} - x = -\cos 2t$$

$$\Rightarrow (5) \boxed{\ddot{x} + x = \cos 2t}$$

hom. DGL: $z^2 + 1 = 0 \Rightarrow z_{1/2} = \pm i$

F.S. $\{ \sin t, \cos t \}$

$$y_h = C_1 \sin t + C_2 \cos t$$

inhom. DGL:

Ansatz
$$\left. \begin{aligned} y_p &= A_1 \cos 2t + A_2 \sin 2t \\ y_p' &= -2A_1 \sin 2t + 2A_2 \cos 2t \\ y_p'' &= -4A_1 \cos 2t - 4A_2 \sin 2t \end{aligned} \right\} (*)$$

$$(*) \text{ in } (5): -4A_1 \cos 2t - 4A_2 \sin 2t + A_1 \cos 2t + A_2 \sin 2t = \cos 2t$$

$$\Rightarrow \cos 2t (-4A_1 + A_1) = \cos 2t$$

$$+ \sin 2t (-4A_2 + A_2)$$

$$\Rightarrow_{KV} \quad \boxed{A_1 = -\frac{1}{3}} \quad , \quad \boxed{A_2 = 0}$$

$$\Rightarrow x_p = -\frac{1}{3} \cos 2t$$

$$\Rightarrow x_{\text{allg}} = x_p + x_h \Rightarrow (6) \quad \boxed{x_{\text{allg}} = C_1 \sin t + C_2 \cos t - \frac{1}{3} \cos 2t}$$

$$(1) \Leftrightarrow (7): \quad y = -\dot{x} + \sin 2t$$

$$\bullet (6) \Rightarrow (8): \quad \dot{x} = C_1 \cos t - C_2 \sin t + \frac{2}{3} \sin 2t$$

$$(8) \text{ in } (7): \quad y = -C_1 \cos t + C_2 \sin t - \frac{2}{3} \sin 2t + \sin 2t$$

$$\Rightarrow y = -C_1 \cos t + C_2 \sin t + \frac{1}{3} \sin 2t$$

$$\left. \begin{array}{l} x(0) = 1 \\ x(0) = C_2 - \frac{1}{3} \end{array} \right\} \Rightarrow \boxed{C_2 = \frac{4}{3}}$$

$$\left. \begin{array}{l} y(0) = 0 \\ y(0) = -C_1 \end{array} \right\} \Rightarrow C_1 = 0$$

$$\begin{aligned} \Rightarrow \begin{pmatrix} x(t) \\ y(t) \end{pmatrix} &= \begin{pmatrix} \frac{4}{3} \cos t - \frac{1}{3} \cos 2t \\ \frac{4}{3} \sin t + \frac{1}{3} \sin 2t \end{pmatrix} \\ &= \frac{4}{3} \begin{pmatrix} \cos t \\ \sin t \end{pmatrix} + \frac{1}{3} \begin{pmatrix} -\cos 2t \\ \sin 2t \end{pmatrix} \end{aligned}$$

A23

$$\dot{x} = Ax \quad \text{mit} \quad A = \begin{pmatrix} 1 & -1 \\ \alpha & -3 \end{pmatrix}$$

$$|A - \lambda E| = 0 \Leftrightarrow \begin{vmatrix} 1-\lambda & -1 \\ \alpha & -3-\lambda \end{vmatrix} = 0$$

$$\Leftrightarrow \boxed{\lambda^2 + 2\lambda - 3 + \alpha = 0}$$

$$\lambda_{1/2} = -1 \pm \sqrt{4 - \alpha}$$

$$2 \text{ reell} \Leftrightarrow 4 - \alpha \geq 0 \Leftrightarrow \boxed{\alpha \leq 4}$$

$$2 \text{ imaginär} \Leftrightarrow \boxed{\alpha > 4}$$

2 reell:

$$\boxed{\alpha = 4} : \lambda_1 = \lambda_2 = -1$$

$(\alpha \leq 4)$

$$\{e^{-t}, t \cdot e^{-t}\} \rightarrow 0 \quad (t \rightarrow \infty)$$

(System stabil)

$$\boxed{\alpha < 4}$$

$$\lambda_{1/2} = -1 \pm \sqrt{4 - \alpha}$$

$$\{e^{\lambda_1 t}, e^{\lambda_2 t}\}$$

$$\text{System stabil} \Leftrightarrow \lambda_{1/2} < 0$$

$$\Leftrightarrow -1 \pm \sqrt{4 - \alpha} < 0 \Leftrightarrow \pm \sqrt{4 - \alpha} < 1$$

$$\Leftrightarrow 4 - \alpha < 1 \Leftrightarrow \boxed{\alpha > 3}$$

2 imaginär:

$(\alpha > 4)$

$$\lambda_{1/2} = -1 \pm j\sqrt{\alpha - 4}$$

$$\{e^{-t} \cos \sqrt{\alpha - 4} \cdot t; e^{-t} \sin \sqrt{\alpha - 4} \cdot t\}$$

$\rightarrow 0 \quad (t \rightarrow \infty) \quad \forall \alpha \in \mathbb{R}$

\Rightarrow System stabil für $\boxed{\forall \alpha > 3}$

A24, S. 88

$$\ddot{x}_1 + 2ax_1 + ax_2 + bx_1' = \cos \omega t$$

$$\ddot{x}_2 + 2ax_2 + ax_1 + bx_2' = 0$$

$$\{z_1 = x_1, z_2 = x_1', z_3 = x_2, z_4 = x_2'\}$$

$$x_1 = z_1$$

$$\dot{x}_1 = \dot{z}_1 = z_2$$

$$\ddot{x}_1 = \ddot{z}_1 = -2az_1 - az_3 - bz_2 + \cos \omega t$$

$$\dot{x}_2 = \dot{z}_3 = z_4$$

$$\ddot{x}_2 = \ddot{z}_3 = -2az_3 - az_1 - bz_4$$

$$\Rightarrow \underline{\dot{z}} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ -2a & -b & -a & 0 \\ 0 & 0 & 0 & 1 \\ -a & 0 & -2a & -b \end{pmatrix} \underline{z} + \begin{pmatrix} 0 \\ \cos \omega t \\ 0 \\ 0 \end{pmatrix}$$

A25

$$(1) \ddot{x} + 3\dot{x} - 2\dot{y} = 0 \Rightarrow (3) \ddot{x} + 3\dot{x} - 2\dot{y} = 0$$

$$(2) \ddot{y} + 3\dot{y} + 2\dot{x} = 0 \Rightarrow (4) \ddot{x} + 3\dot{x} - 2\ddot{y} = 0$$

$$(2) \Rightarrow (5) \ddot{y} + 3\dot{y} + 2\dot{x} = 0 \Rightarrow (6) \ddot{y} = -3\dot{y} - 2\dot{x}$$

$$(1) \Leftrightarrow 2\dot{y} = \ddot{x} + 3\dot{x} \Leftrightarrow (7) \dot{y} = \frac{\ddot{x}}{2} + \frac{3}{2}\dot{x}$$

$$(6) \text{ in } (4): \ddot{x} + 3\ddot{x} + 6\dot{y} + 4\dot{x} = 0$$

$$\Leftrightarrow (8) \ddot{x} + 7\ddot{x} + 6\dot{y} = 0$$

$$(7) \text{ in } (8): \ddot{x} + 7\ddot{x} + 3\ddot{x} + 9\dot{x} = 0$$

$$\Leftrightarrow \boxed{\ddot{x} + 10\ddot{x} + 9\dot{x} = 0}$$

$$\text{char. Pol.: } \lambda^4 + 10\lambda^2 + 9 = 0$$

$$w := \lambda^2 \Rightarrow w^2 + 10w + 9 = 0$$

$$\Rightarrow w_{1/2} = \frac{-10 \pm \sqrt{100 - 36}}{2} \Rightarrow w_1 = -1, w_2 = -9$$

$$\Rightarrow \lambda^2 = -1 \Rightarrow \lambda_1 = i, \lambda_2 = -i$$

$$\lambda^2 = -9 \Rightarrow \lambda_3 = 3i, \lambda_4 = -3i$$

$$\text{F.S. } \{ \cos t, \sin t, \cos 3t, \sin 3t \}$$

\Rightarrow allg. Lsg.

$$(9) x(t) = C_1 \cos t + C_2 \sin t + C_3 \sin 3t + C_4 \cos 3t$$

$$\Rightarrow \dot{x}(t) = -C_1 \sin t + C_2 \cos t + 3C_3 \cos 3t - 3C_4 \sin 3t$$

(10)

$$\Rightarrow (11) \ddot{x}(t) = -C_1 \cos t - C_2 \sin t - 9C_3 \sin 3t - 9C_4 \cos 3t$$

(10), (11) in (7): $\dot{y} = \frac{\ddot{x}}{2} + \frac{3}{2}x$

$$\Rightarrow \dot{y} = \underbrace{-\frac{C_1}{2} \cos t - \frac{C_2}{2} \sin t - \frac{9}{2} C_3 \sin 3t - \frac{9}{2} C_4 \cos 3t}_{\text{from (11)}} + \underbrace{\frac{3}{2} C_1 \cos t + \frac{3}{2} C_2 \sin t + \frac{3}{2} C_3 \sin 3t + \frac{3}{2} C_4 \cos 3t}_{\text{from (9)}}$$

$$= C_1 \cos t + C_2 \sin t - 3C_3 \sin 3t - 3C_4 \cos 3t$$

$$\Rightarrow y = C_1 \sin t - C_2 \cos t + C_3 \cos 3t - C_4 \sin 3t$$

$$\left. \begin{array}{l} x(0) = 1 \\ x(0) = C_1 + C_4 \end{array} \right\} \Rightarrow \boxed{C_1 + C_4 = 1}$$

$$\left. \begin{array}{l} \dot{x}(0) = 0 \\ \dot{x}(0) = C_2 + 3C_3 \end{array} \right\} \Rightarrow \boxed{C_2 + 3C_3 = 0}$$

$$\left. \begin{array}{l} y(0) = 0 \\ y(0) = -C_2 + C_3 \end{array} \right\} \Rightarrow \boxed{-C_2 + C_3 = 0}$$

$$\left. \begin{array}{l} \dot{y}(0) = 1 \\ \dot{y}(0) = C_1 - 3C_4 \end{array} \right\} \Rightarrow \boxed{C_1 - 3C_4 = 1}$$

$$\boxed{C_4 = 0}$$

$$\boxed{C_1 = 1}$$

$$\boxed{C_3 = 0}$$

$$\boxed{C_2 = 0}$$

A26

$$\lambda_1 = -1 + j \text{ ist EW} \Rightarrow \lambda_2 = -1 - j \text{ ist EW}$$

$$\text{d. char. Polynom von } |A - \lambda E| = 0$$

alg. Lsg.:

$$\underline{\tilde{x}} = \begin{pmatrix} 1 \\ j \end{pmatrix} e^{-t} (\cos t + j \sin t)$$

$$= e^{-t} \begin{pmatrix} \cos t + j \sin t \\ -\sin t + j \cos t \end{pmatrix}$$

$$= \underbrace{e^{-t} \begin{pmatrix} \cos t \\ -\sin t \end{pmatrix}}_{=: \underline{x}^{(1)}} + j \underbrace{e^{-t} \begin{pmatrix} \sin t \\ \cos t \end{pmatrix}}_{=: \underline{x}^{(2)}}$$

$$\underline{x}^{(1)} = \operatorname{Re}(\underline{\tilde{x}})$$
$$\underline{x}^{(2)} = \operatorname{Im}(\underline{\tilde{x}})$$

$$\Rightarrow \text{alg. Lsg: } \underline{x}(t) = k_1 \underline{x}^{(1)} + k_2 \underline{x}^{(2)} \quad (k_1, k_2 \in \mathbb{R})$$

$$\underline{\dot{x}}^{(1)} = \begin{pmatrix} -e^{-t} \cos t - e^{-t} \sin t \\ e^{-t} \sin t - e^{-t} \cos t \end{pmatrix} = e^{-t} \begin{pmatrix} \cos t - \sin t \\ \sin t - \cos t \end{pmatrix}$$

$$\underline{x}^{(1)}, \underline{\dot{x}}^{(1)} \text{ in } \underline{\dot{x}} = A \underline{x} :$$

$$e^{-t} \begin{pmatrix} -\cos t - \sin t \\ \sin t - \cos t \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & -1 \end{pmatrix} \begin{pmatrix} \cos t \\ -\sin t \end{pmatrix} e^{-t}$$

$$a_{11} = -1$$

$$\Rightarrow \left. \begin{aligned} -\cos t - \sin t &= a_{11} \cos t - a_{12} \sin t \\ \sin t - \cos t &= a_{21} \cos t + \sin t \end{aligned} \right\} \Rightarrow \text{kv.}$$

$$a_{12} = 1$$

$$a_{21} = -1$$

$$\begin{aligned} \rightarrow \quad x(t) &= \cos t \\ y(t) &= \sin t \end{aligned}$$